

Câu 1: (2 điểm)

a)

$$\lambda_x = \cos \theta_x = \frac{x_F - x_N}{L} = \frac{x_F - x_N}{\sqrt{(x_F - x_N)^2 + (y_F - y_N)^2}}$$

$$\lambda_y = \cos \theta_y = \frac{y_F - y_N}{L} = \frac{y_F - y_N}{\sqrt{(x_F - x_N)^2 + (y_F - y_N)^2}}$$

$$\mathbf{T} = \begin{bmatrix} \lambda_x & \lambda_y & 0 & 0 \\ 0 & 0 & \lambda_x & \lambda_y \end{bmatrix} \quad (14-9)$$

From the above derivation, \mathbf{T} transforms the four global x, y displacements \mathbf{D} into the two local x' displacements \mathbf{d} . Hence, \mathbf{T} is referred to as the *displacement transformation matrix*.

$$\mathbf{T}^T = \begin{bmatrix} \lambda_x & 0 \\ \lambda_y & 0 \\ 0 & \lambda_x \\ 0 & \lambda_y \end{bmatrix} \quad (14-12)$$

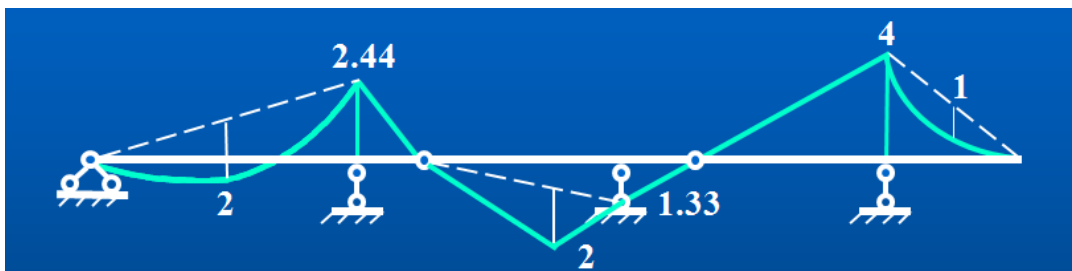
In this case \mathbf{T}^T transforms the two local (x') forces \mathbf{q} acting at the ends of the member into the four global (x, y) force components \mathbf{Q} . By comparison, this *force transformation matrix* is the transpose of the displacement transformation matrix, Eq. 14–9.

b) Geometrically stable

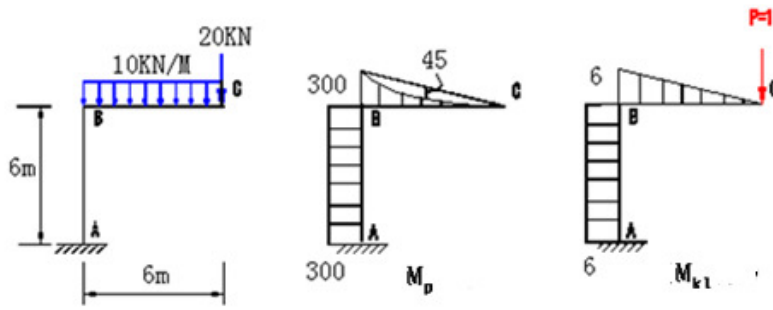
Câu 2: (2 điểm)

$$N_a = N_b = P/8\sin\alpha$$

Câu 3: (2 điểm)



Câu 4: (2 điểm)



$$\Delta_{CV} = \int_l \frac{\bar{M}_K M_P}{EI} ds = \frac{1}{EI} \left[\left(\frac{6 \times 6}{2} \right) \times \left(\frac{2 \times 300}{3} \right) - \left(\frac{2}{3} \times 6 \times 45 \right) \times \left(\frac{6}{2} \right) + (6 \times 6) \times (300) \right] = \frac{13860}{EI} = 0.0924 m (\downarrow)$$

Câu 5: (2 điểm)

